



FLOWHEAD

Fluid Optimisation Workflows for Highly Effective Automotive Development Processes

**Workshop on industrial design optimisation for fluid flow,
Varna, BG,
22-24 Sep 2010**

**Automated process for CFD simulation with Starccm+,
from CAD surface to postprocessing**

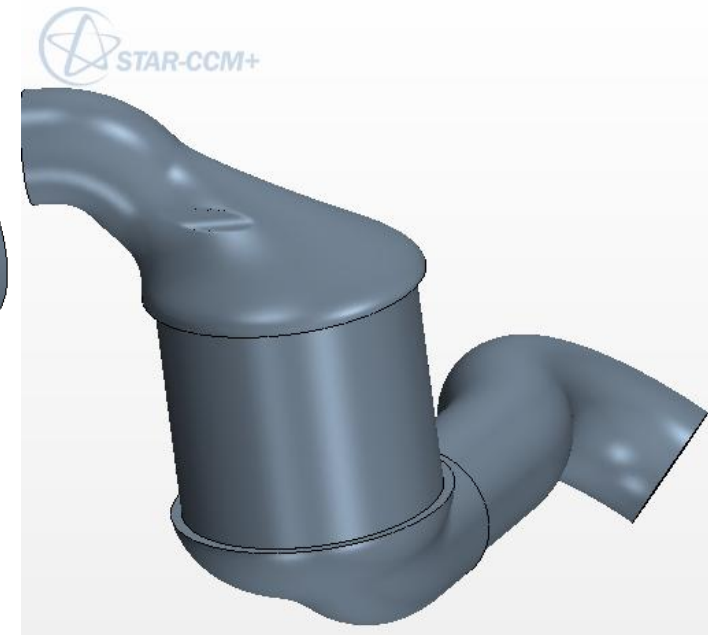
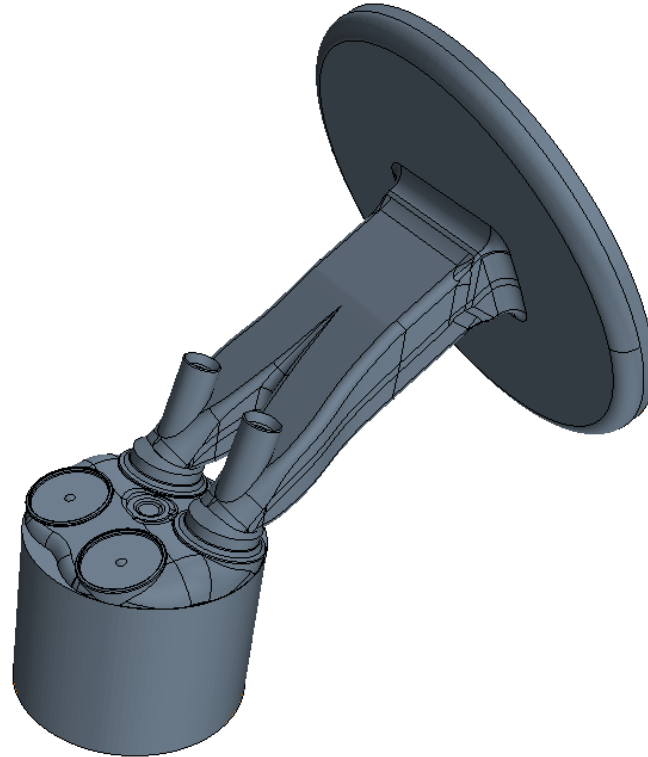
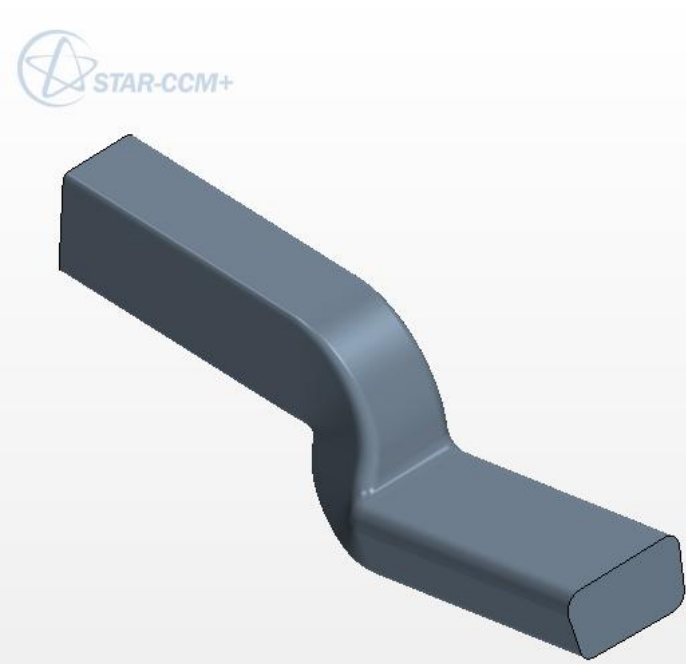
Alexandre CANO - Wednesday, 22 September

Overview

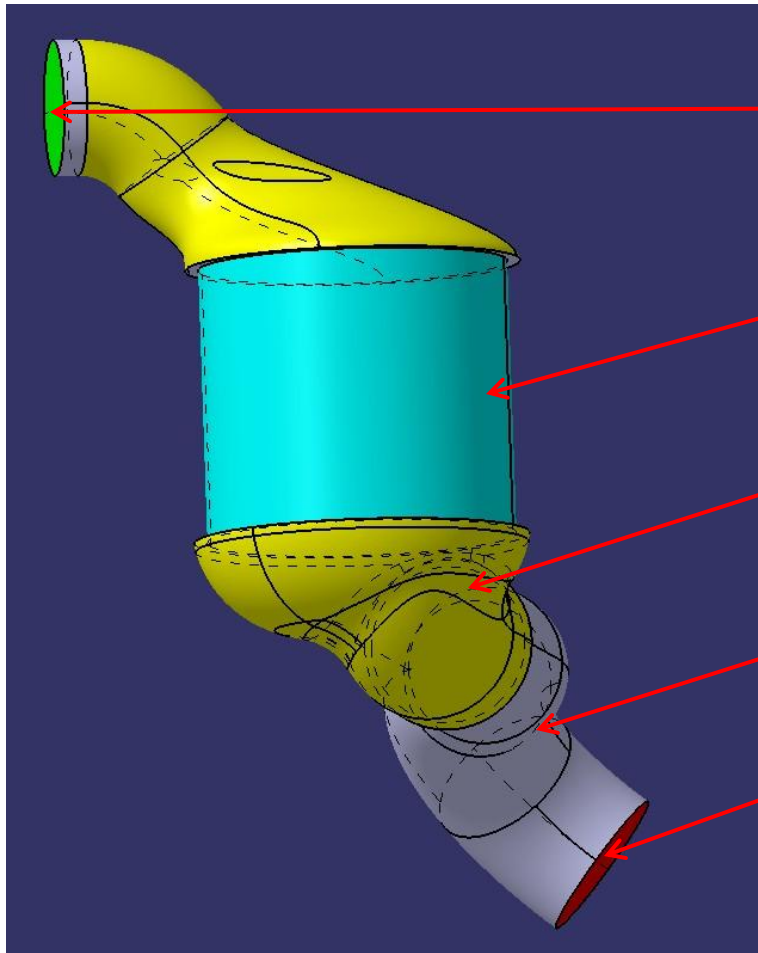
- CAD surface of the demonstration case
- The workflow Automated CFD process
- Automation – The meshing
- Automation – The boundary conditions
- Automation – The physics and solver setup
- Automation – The run
- Automation – The post processing
- Macro Java Parameters
- Conclusion

CAD surface of the demonstration case

- Full automated process performed on 3 test cases



CAD surface of the demonstration case : The Catalyst



Inlet

Porous medium

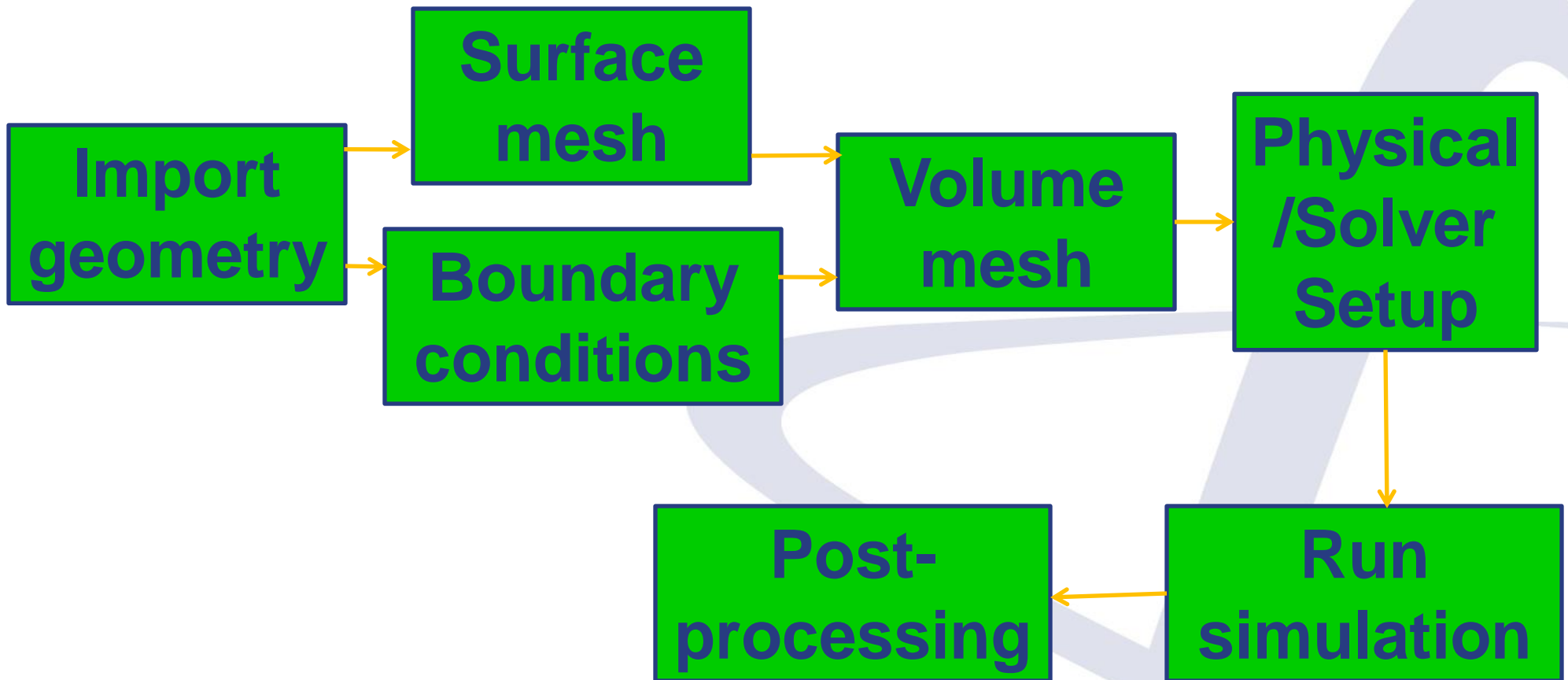
optimized zones (yellow parts)

Fixed zones (grey parts)

Outlet

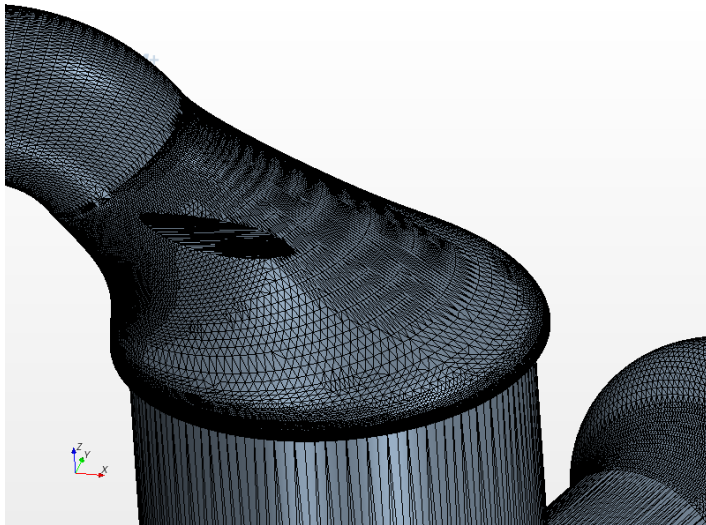
**Objective functions : pressure drop
and flow uniformity**

The workflow Automated CFD process



Automation – The meshing

- First the import surface (CATPart in this example)
- Boundary condition surfaces: Split by angle, locations and areas



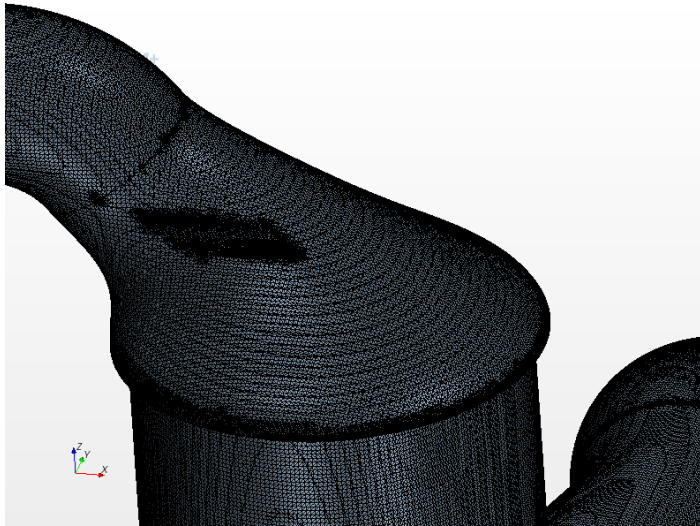
Import surface



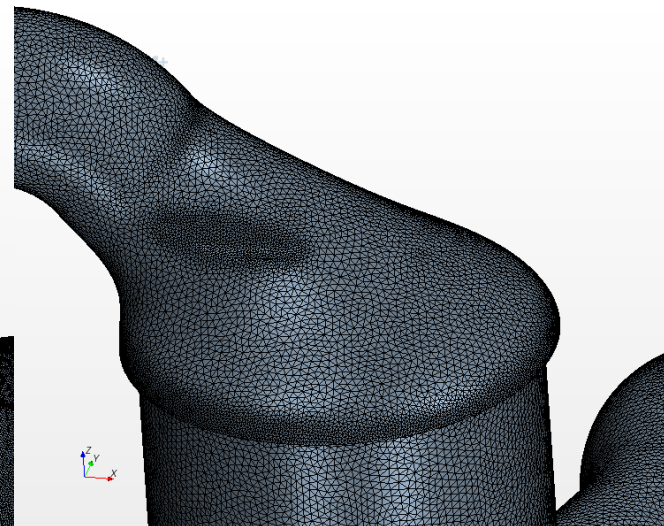
**Inlet, outlet, interfaces
with porous region**

Automation – The meshing

- The meshing generation is divided into 2 parts
 - Surface mesh : Wrap and remesh the surface
 - Volume mesh
- The base size is 3mm



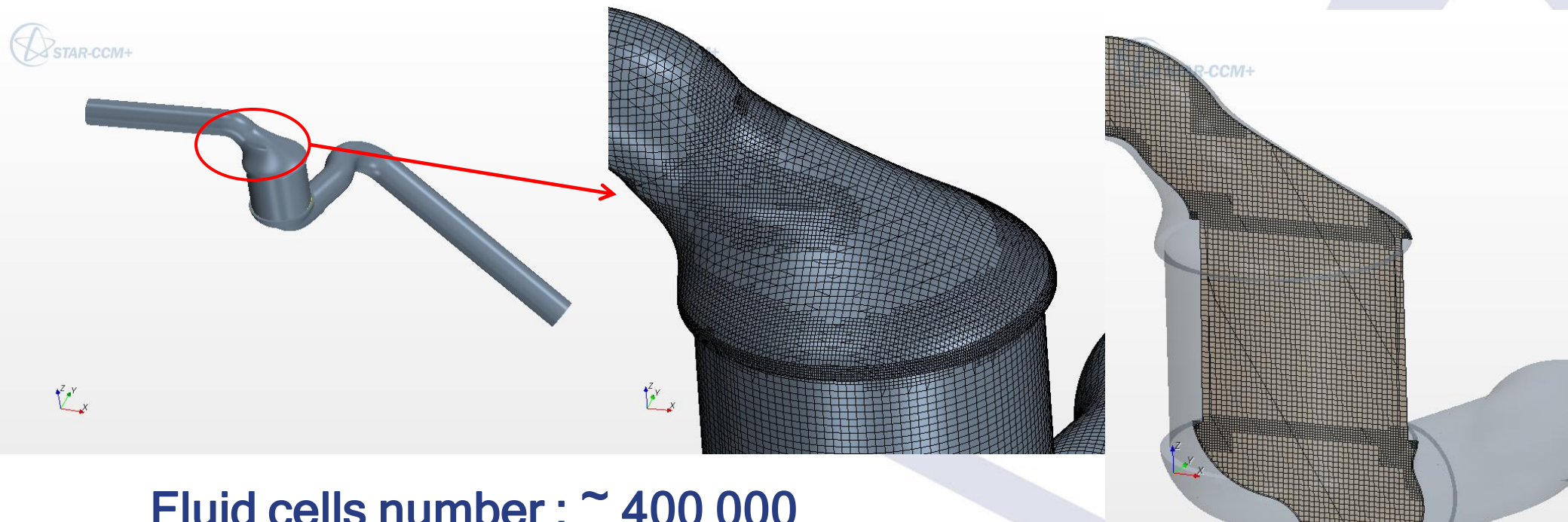
wrapping



remesh

Automation – The meshing

- The volume mesh is an assemble of a core trimmed mesh and an extrusion layer.



Fluid cells number : $\sim 400\ 000$

Elapsed time mesh generation (surface + volume): 3 minutes

(laptop machine : Intel Core 2 Duo 2.59 GHz, 3.5Go de RAM)

Automation – The boundary conditions (physical values)

Mass flow Inlet

$$Q_m = 0.26841 \text{ kg/s}$$

$$T = 923.15 \text{ K}$$

Porous medium

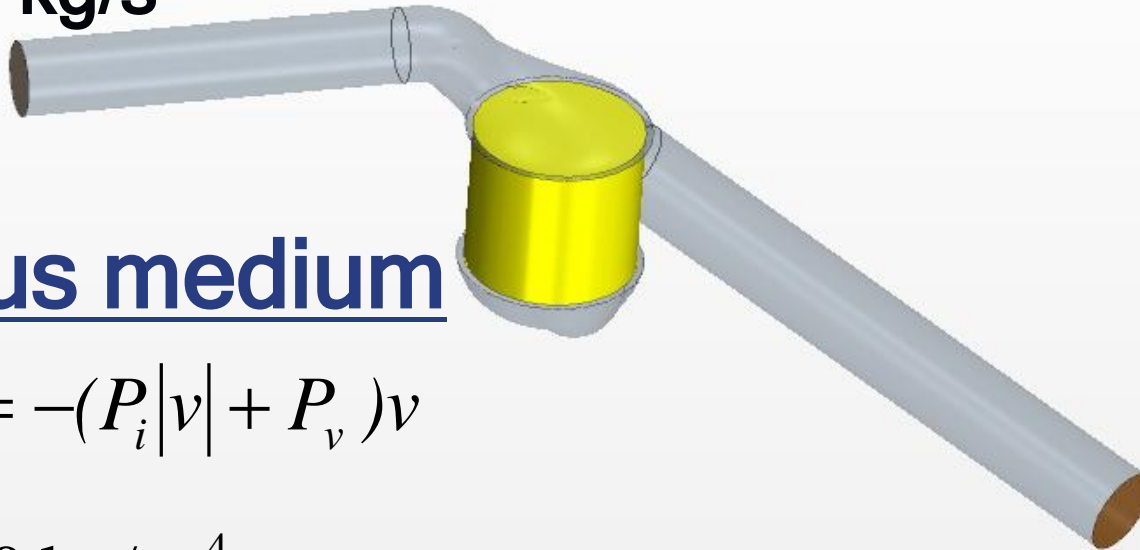
$$\frac{\Delta p}{L} = -(P_i |v| + P_v) v$$

$$P_i = 0 \text{ kg/m}^4$$

$$P_v = 2298.0 \text{ kg/m}^3$$

Pressure outlet

$$P_s = 0. \text{ Pa}$$

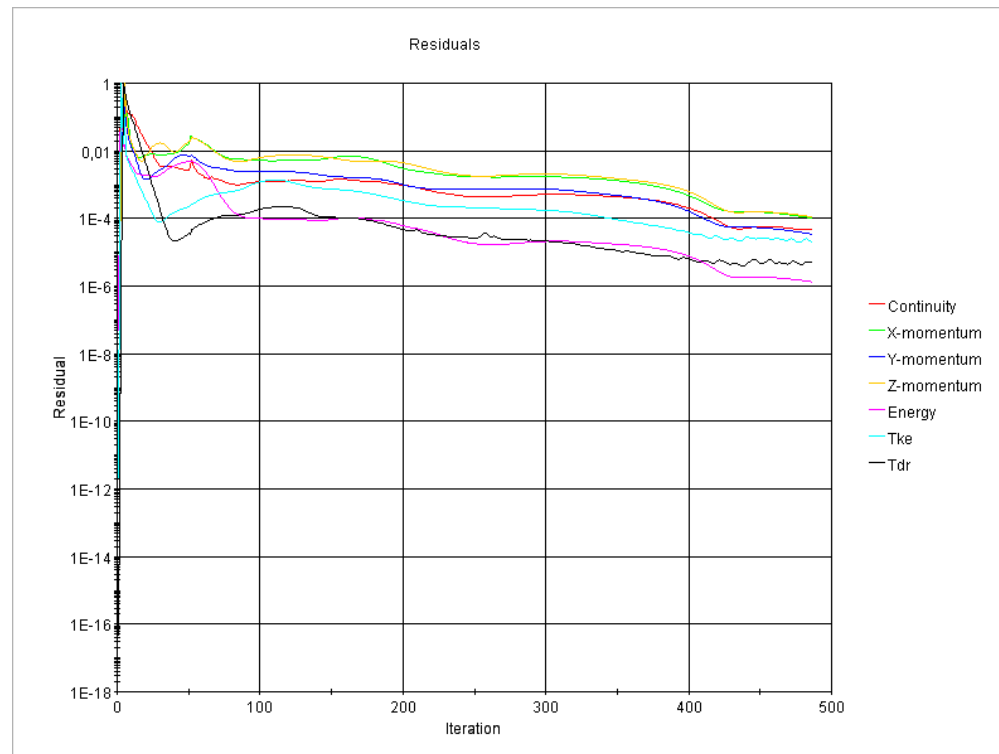


Automation – The physics and solver setup

- Physics setup
 - Steady simulation
 - Fluid properties : Air
 - Equation of state : Ideal gas
 - Viscous regime : Turbulent, K-Epsilon high Reynolds
- Solver setup
 - AMG solver
 - 2nd order : velocity, K-Epsilon, Temperature

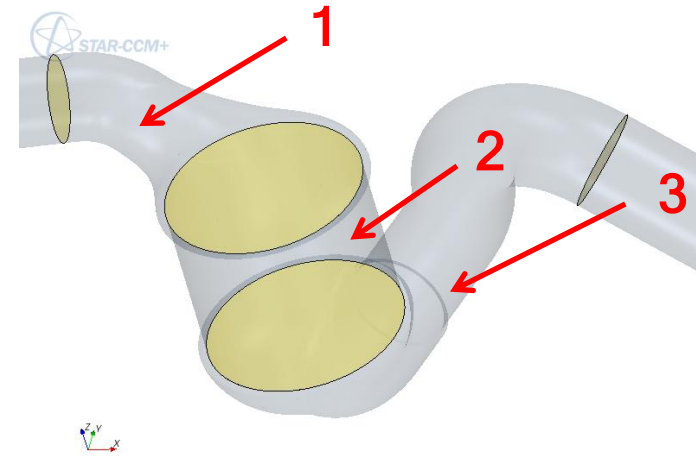
Automation – The run

- Less than 1 hour to converge on 2 CPU (100 iterations / 10 min)
(laptop machine : Intel Core i7 Duo 2.67 GHz, 8Go RAM)



Automation – The post processing

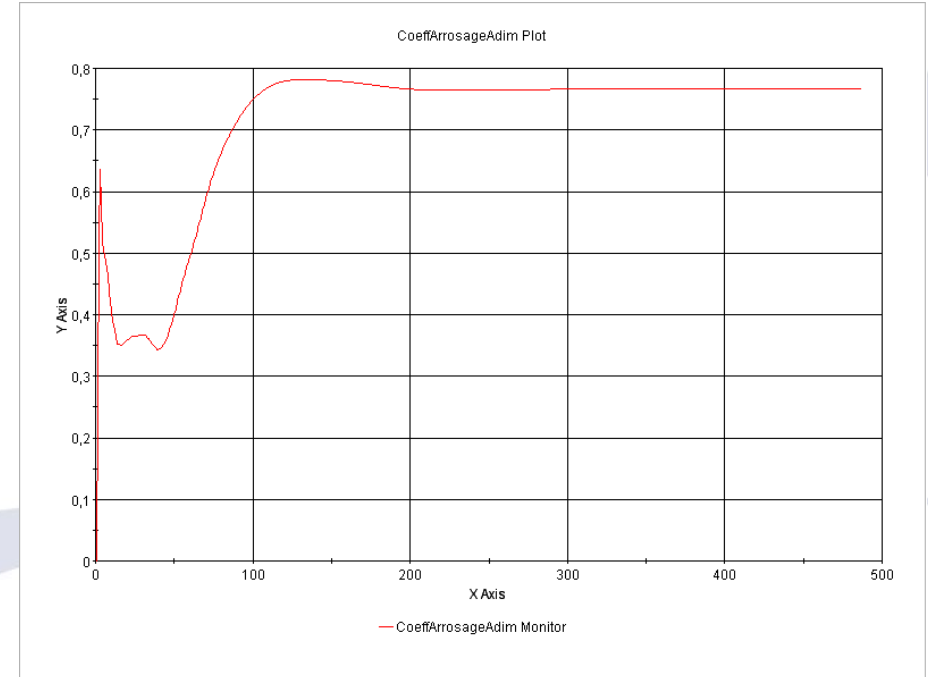
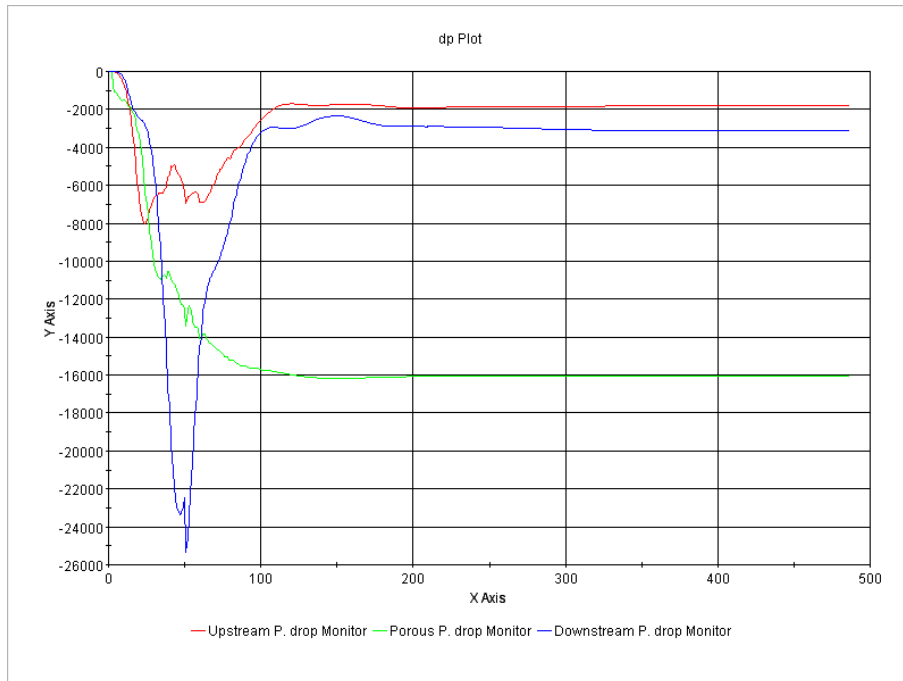
- Pressure drop
 - 1/ Upstream porous
 - 2/ Porous
 - 3/ Downstream porous



- Velocities uniformity normalized by the mean velocity

$$A = \frac{\sqrt{\frac{\sum (V_i - V_{\text{mean}})^2}{\text{Nbcells}}}}{V_{\text{mean}}}$$

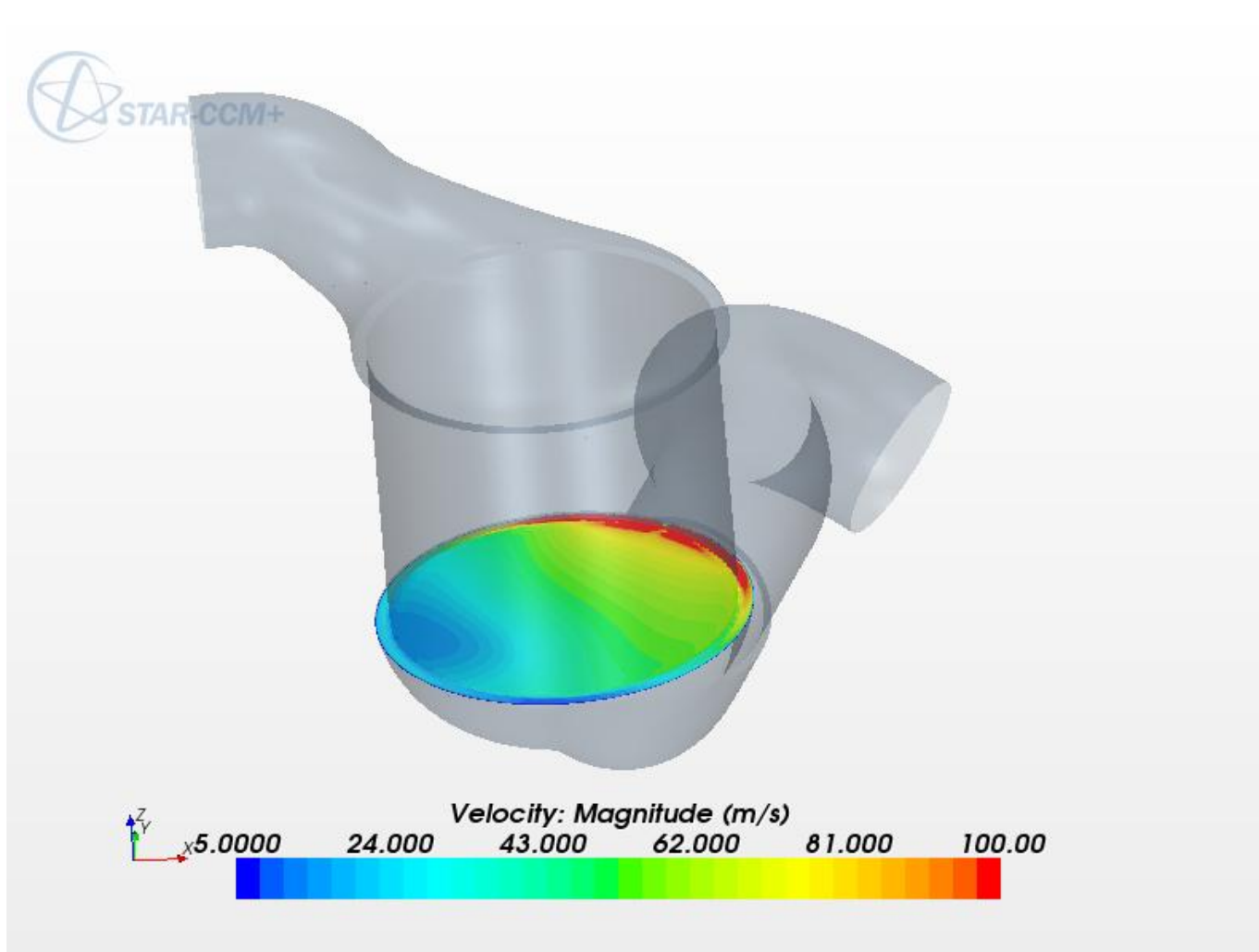
Automation – The post processing



dp1 = 1810 Pa
dp2 = 16050 Pa
dp3 = 3090 Pa

A= 0.76

Automation – The post processing



Macro Java Parameters

// Mesh parameters (size in m unit)

```
double basesize = 3.E-3;  
double minsurface = 33.3; // relative value (%)  
double max_cell_size = 5.E-3;  
double wrapping_factor = 50.0; // relative value (%)  
double prism_layer_thick = 0.75E-3;  
double prism_layer_thick_porous = 4E-3;  
int layer_num = 1;
```

//Upstream geometric extrusion

```
double D_extr_Magnitude = 300E-3; // 5 times the inlet diameter  
int D_extr_NumLayers = 40;  
double D_extr_Stretching = 3.0;
```

// Downstream geometric extrusion

```
double Up_extr_Magnitude = 500E-3; // 8 time the outlet diameter  
int Up_extr_NumLayers = 70;  
double Up_extr_Stretching = 3.0;
```

// Physic Parameters

```
double T_in = 923.15; // K  
double V_in = 222.3; // m/s  
double Mass_flow_in = 0.26841; // kg.s-1  
double Cp_air = 1003.62; // J/kgK  
double Total_T_in = T_in + V_in * V_in / (2*Cp_air); // K  
double beta_axis = 2298.0; // kg.m-3.s in the Z local porous coordinate system  
double porous_conductivity = 0.02637; // W/mK
```

// Maximum iterations

```
int max_iter = 2000;
```

Conclusion

- The java macro creates the mesh, defines the physical and the solver setup and does the post-processing without user intervention.
- Any modifications on the moving zones surfaces are allowed.
- The automated process can be used to evaluate optimisation proposals

Do you have any questions ?